

Noise-assisted sensing

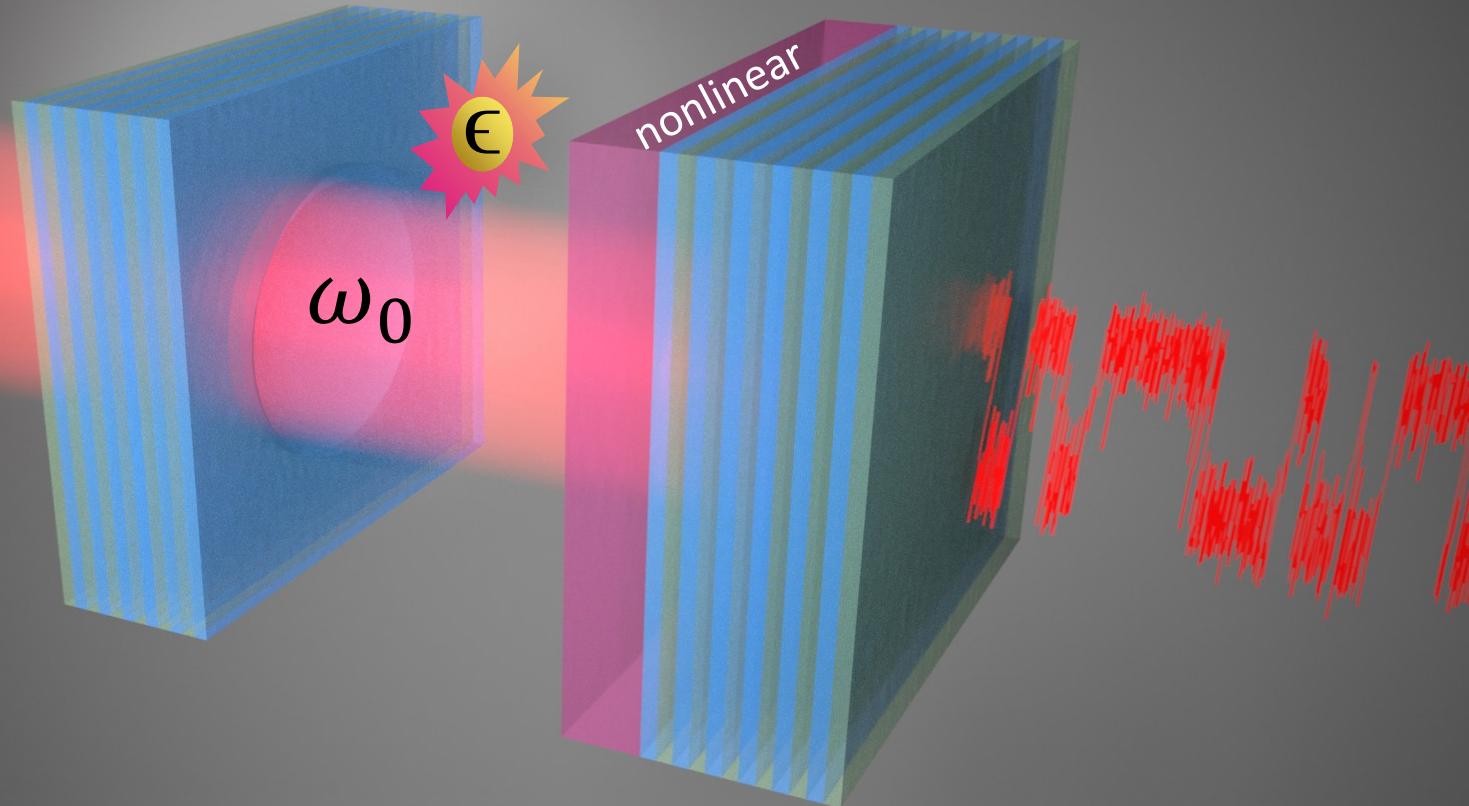
Said R. K. Rodriguez

Dutch Photonics event

September 10, 2019

A bistable cavity as a sensor

- Detection speed and sensitivity enhanced by (quantum) fluctuations



A classical nonlinear cavity

$$i\dot{\alpha} = \left(-\Delta + U(|\alpha|^2 - 1) - i\frac{\Gamma}{2} \right) \alpha + i\sqrt{\kappa_1} F$$

detuning nonlinearity

loss

driving

$$F e^{-i\omega t}$$

$$\omega_0$$

$$U$$

$$\sqrt{\kappa_1}$$

$$\gamma$$

$$\sqrt{\kappa_2}$$

$$\Delta = \omega - \omega_0$$

$$\Gamma = \kappa_1 + \kappa_2 + \gamma$$

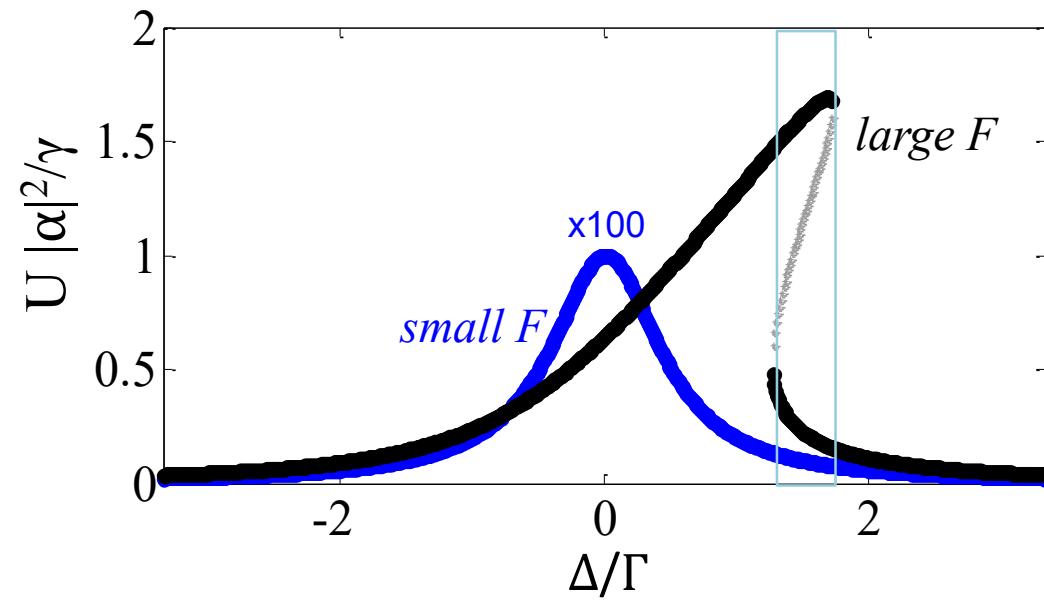
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↑ detuning ↑ nonlinearity ↑ loss ↑ driving

$$\Delta = \omega - \omega_0$$

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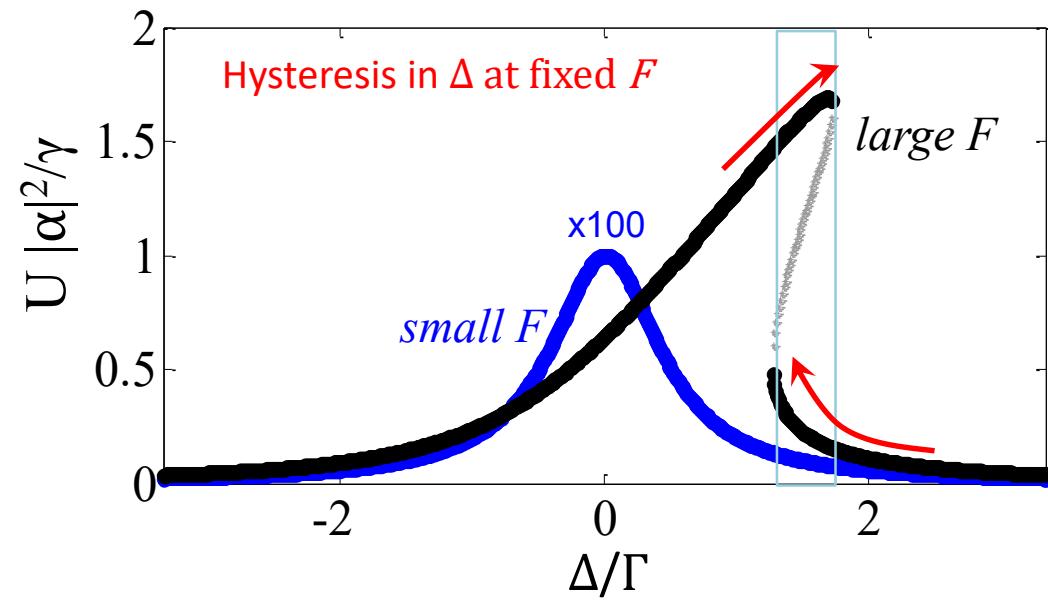
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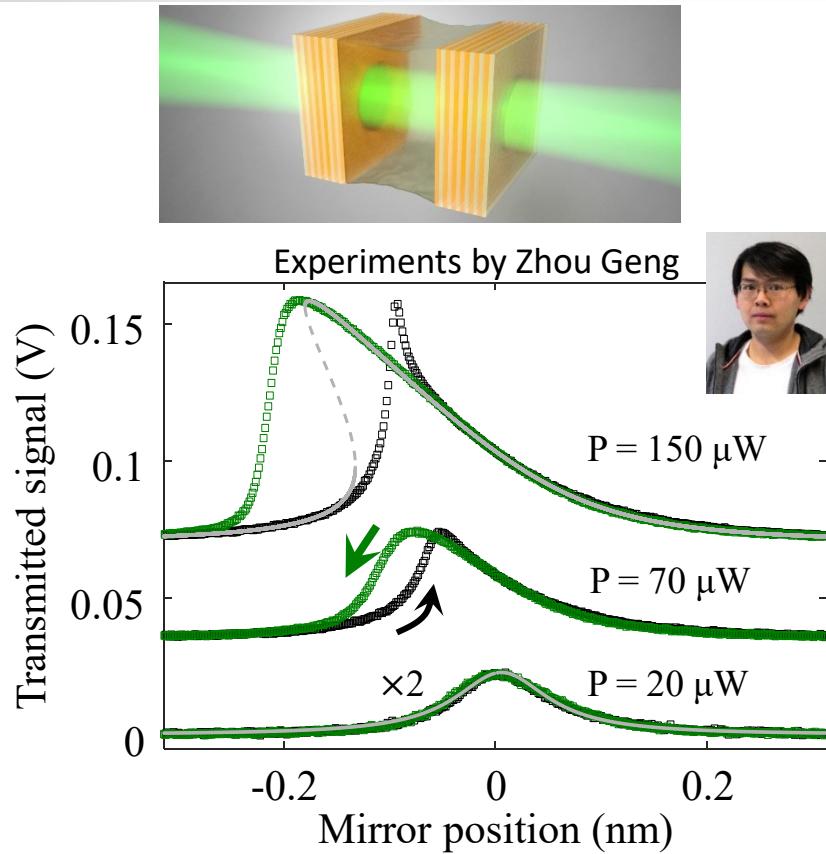
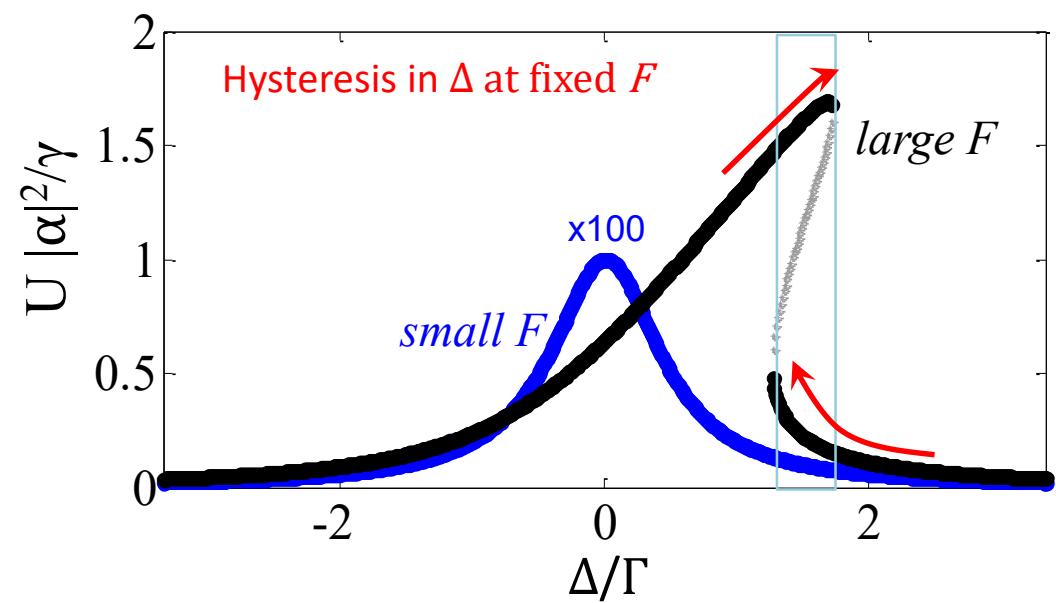
$$\Gamma = \kappa_1 + \kappa_2 + \gamma$$



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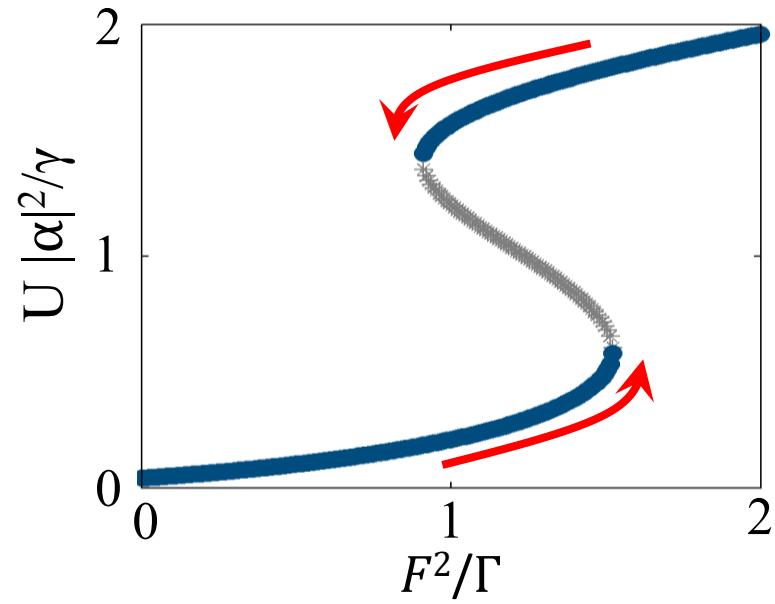
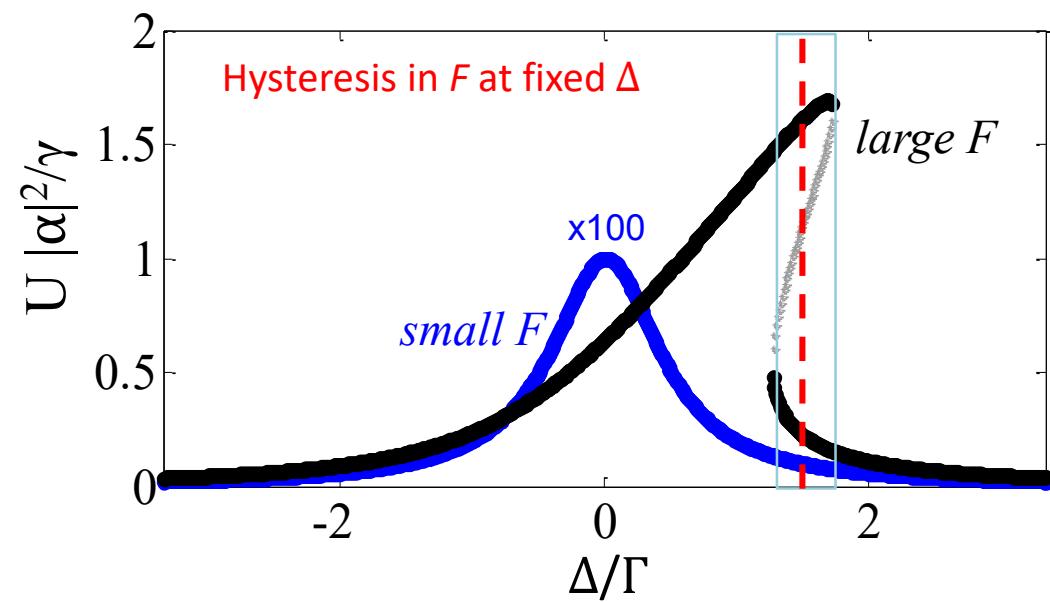
detuning nonlinearity loss driving



A classical nonlinear cavity

$$i\dot{\alpha} = \left(-\Delta + U(|\alpha|^2 - 1) - i\frac{\Gamma}{2} \right) \alpha + i\sqrt{\kappa_1}F$$

↑ detuning ↑ nonlinearity ↑ loss ↑ driving



A quantum nonlinear cavity

$$\hat{H}(t) = \omega_0 \hat{a}^\dagger \hat{a} + \underbrace{\frac{U}{2} \hat{a}^\dagger \hat{a}^\dagger \hat{a} \hat{a}}_{\text{interaction}} + \underbrace{\sqrt{I(t)} (e^{-i\omega t} \hat{a}^\dagger + e^{i\omega t} \hat{a})}_{\text{driving}}$$

$$\frac{\partial \hat{\rho}(t)}{\partial t} = i [\hat{\rho}, \hat{H}(t)] + \underbrace{\frac{\gamma}{2} (2\hat{a}\hat{\rho}\hat{a}^\dagger - \hat{a}^\dagger\hat{a}\hat{\rho} - \hat{\rho}\hat{a}^\dagger\hat{a})}_{\text{loss}}$$

A quantum nonlinear cavity

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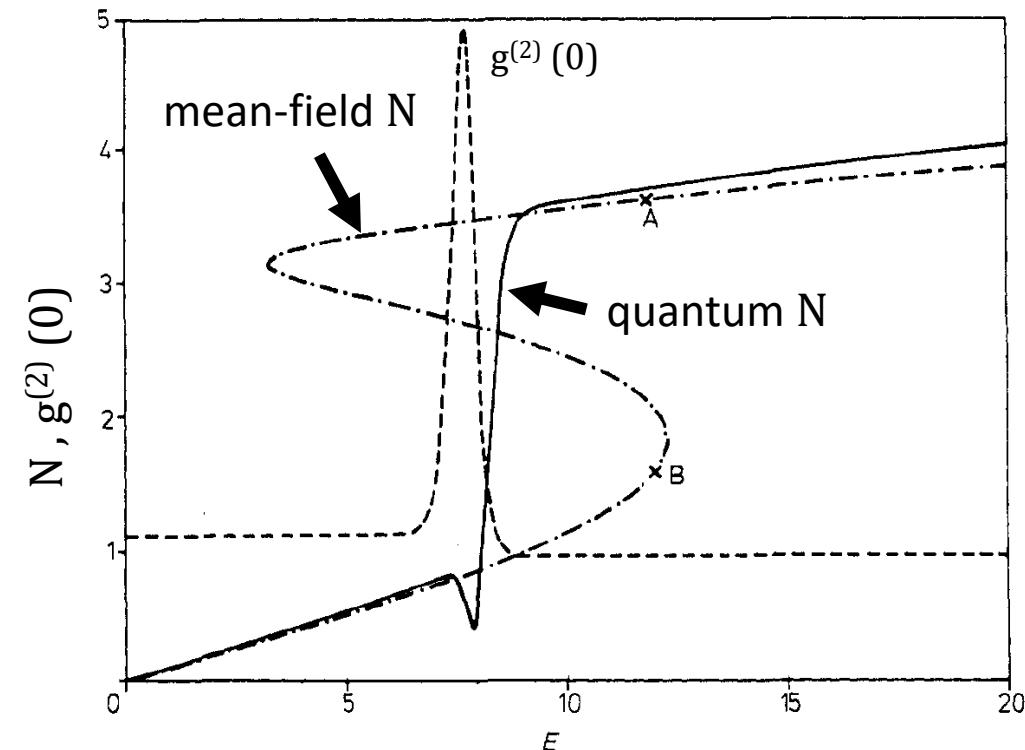
SS density

$$N = \langle \hat{a}^\dagger \hat{a} \rangle = \text{Tr}[\hat{a}^\dagger \hat{a} \hat{\rho}]$$

mean-field approx.

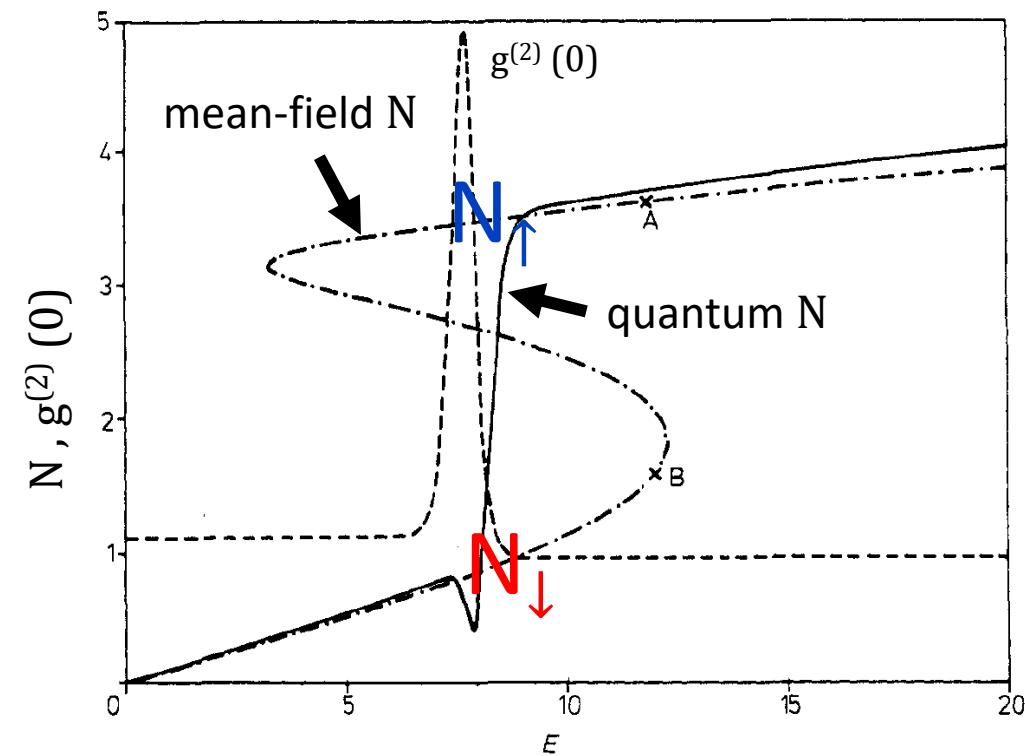
$$N = |\alpha|^2$$

Mean-field bistability vs quantum unique SS



P. D. Drummond & D. F. Walls, J. Phys. A **13**, 725 (1980).

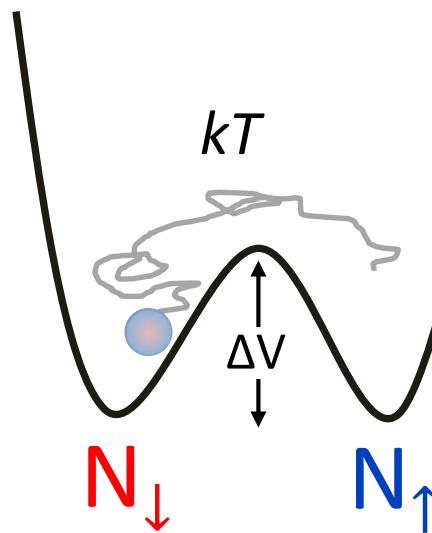
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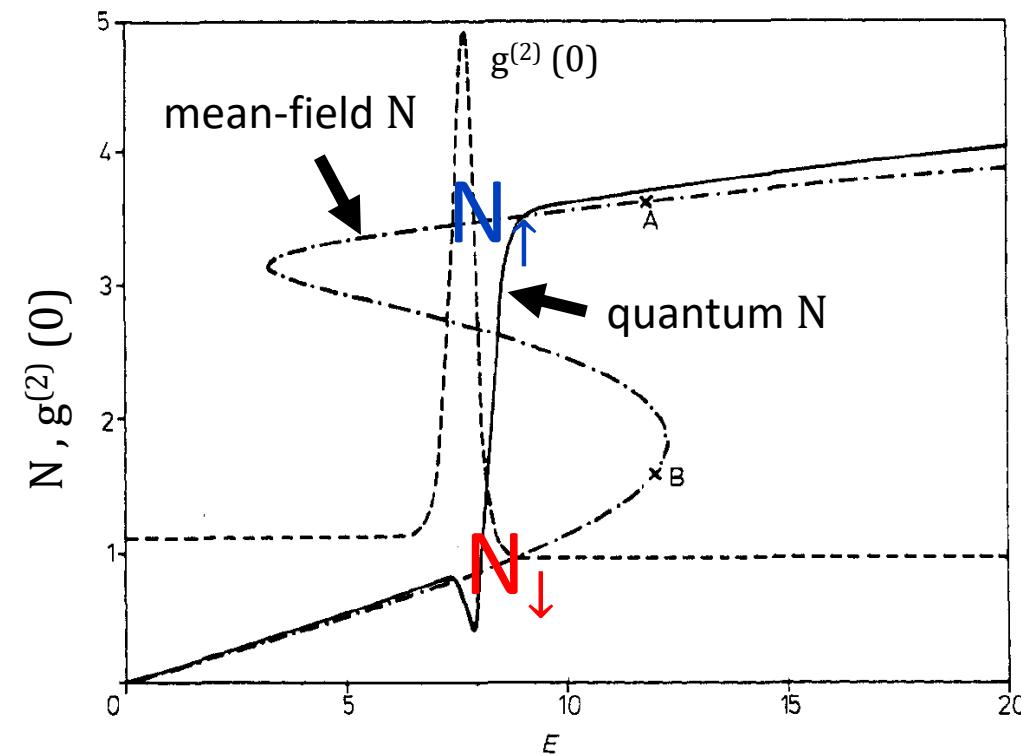
Quantum tunneling in dispersive optical bistability

H. Risken,* C. Savage, F. Haake,[†] and D. F. Walls
Physics Department, University of Waikato, Hamilton, New Zealand
(Received 23 June 1986)



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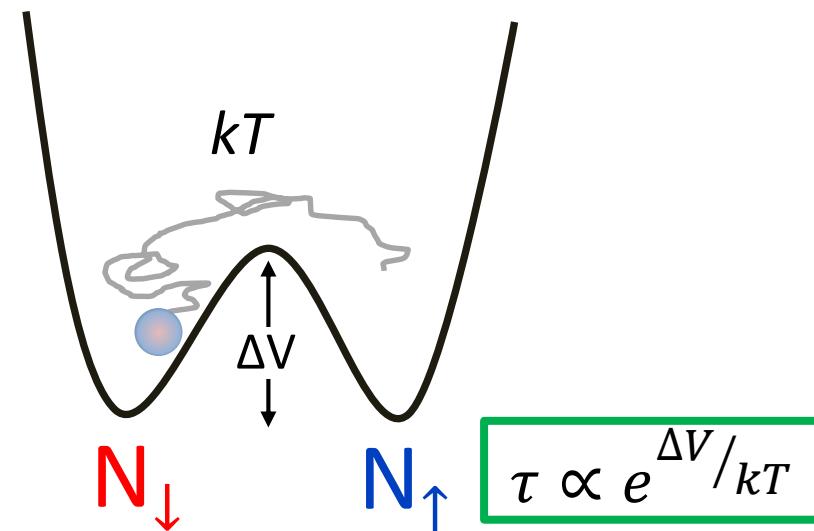
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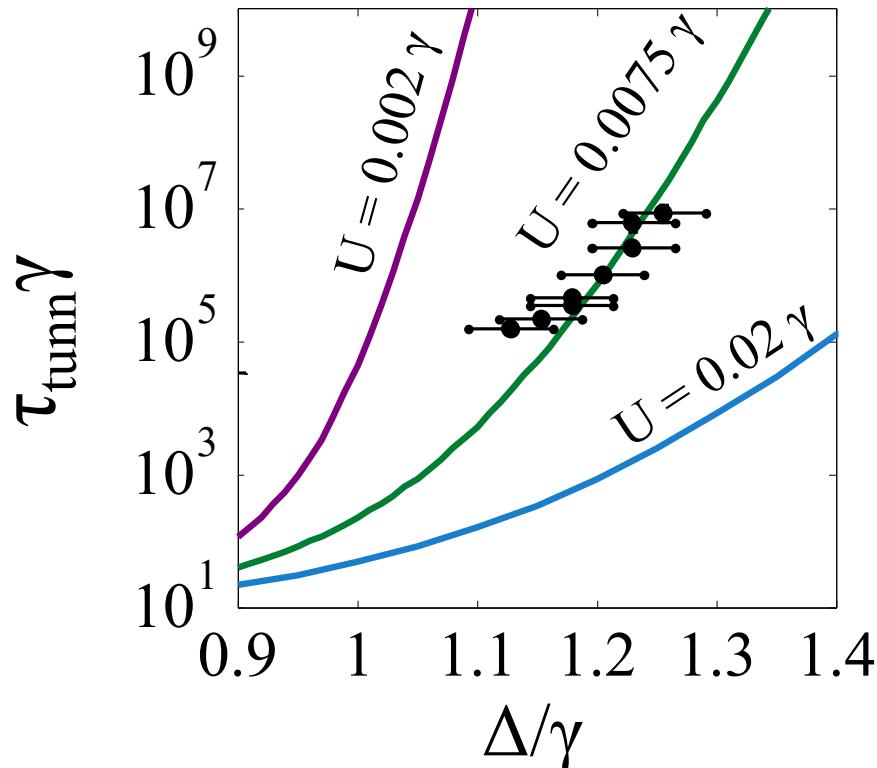
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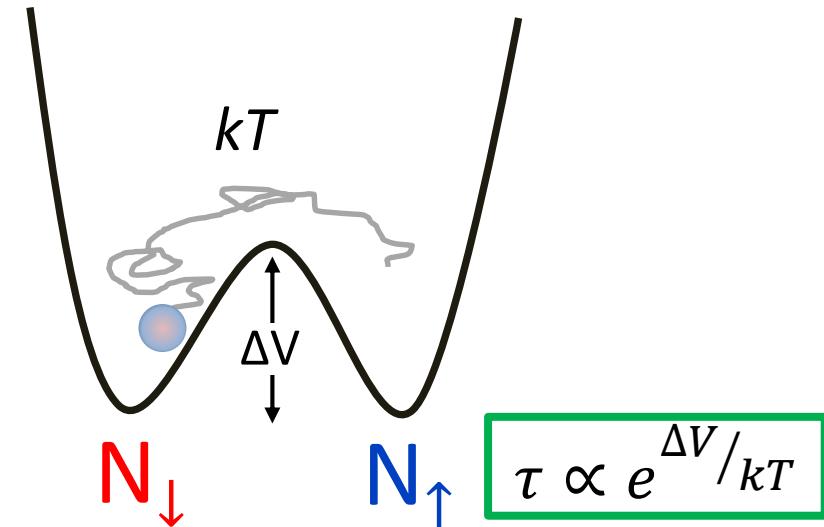
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The influence of noise on a bistable cavity

$$i\dot{\alpha} = \left(-\Delta + U(|\alpha|^2 - 1) - i\frac{\Gamma}{2} \right) \alpha + i\sqrt{\kappa_1}F + D\tilde{\xi}(t)$$

complex white noise

Valid for $U/\Gamma \lesssim 0.2$

$$D = \sqrt{\frac{\Gamma}{2}}$$

Fluctuation-dissipation

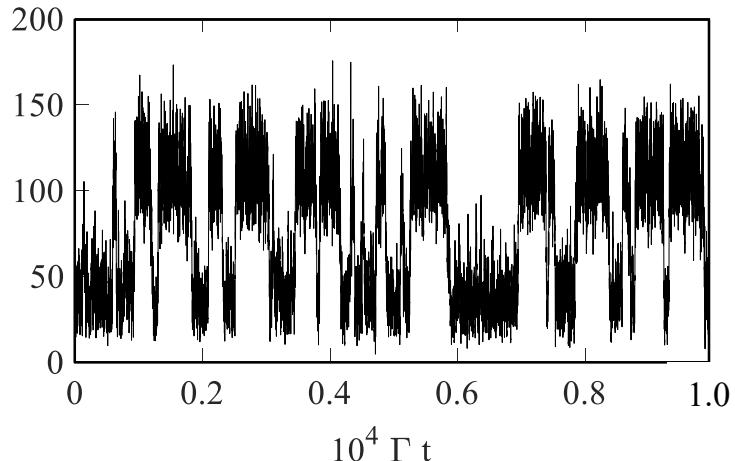
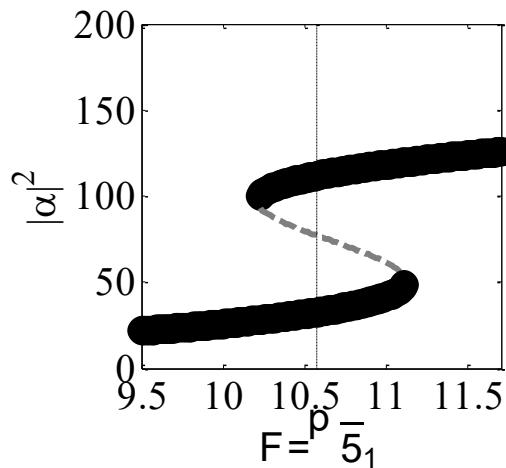
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$$D = \sqrt{\frac{\Gamma}{2}}$$

Fluctuation-dissipation

$$\Delta = 1.1\Gamma$$

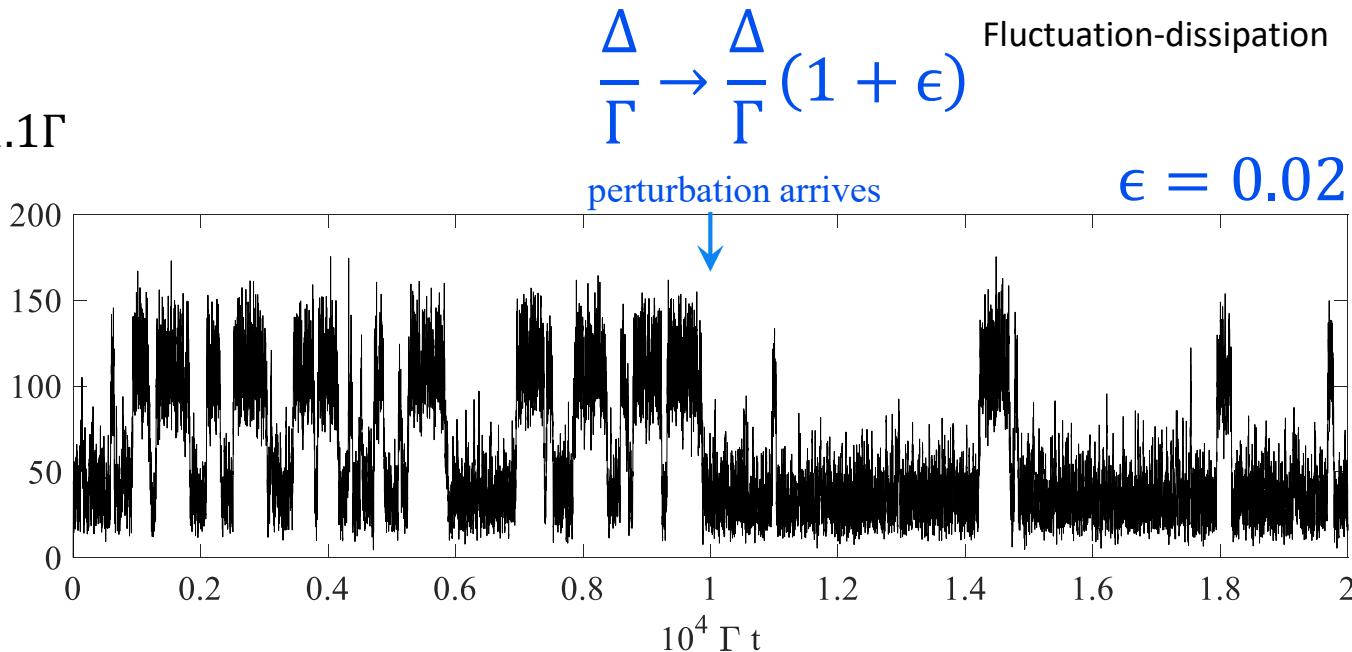
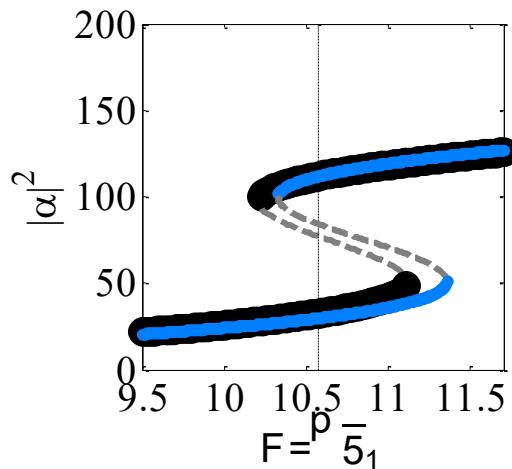


The influence of noise on a bistable cavity

$$i\dot{\alpha} = \left(-\Delta + U(|\alpha|^2 - 1) - i\frac{\Gamma}{2} \right) \alpha + i\sqrt{\kappa_1}F + D\tilde{\xi}(t)$$

$$D = \sqrt{\frac{\Gamma}{2}}$$

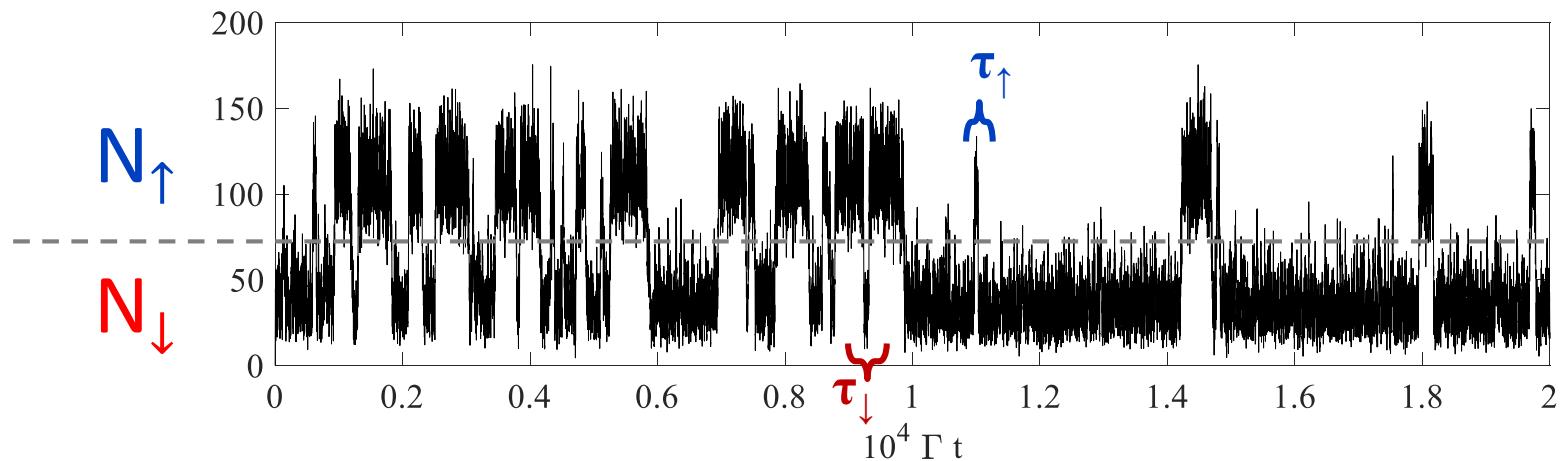
$$\Delta = 1.1\Gamma$$



Sensing based on residence time difference

$$i\dot{\alpha} = \left(-\Delta + U(|\alpha|^2 - 1) - i\frac{\Gamma}{2} \right) \alpha + i\sqrt{\kappa_1}F + D\tilde{\xi}(t)$$

Mean residence time difference: $\delta\tau = \tau_{\uparrow} - \tau_{\downarrow}$



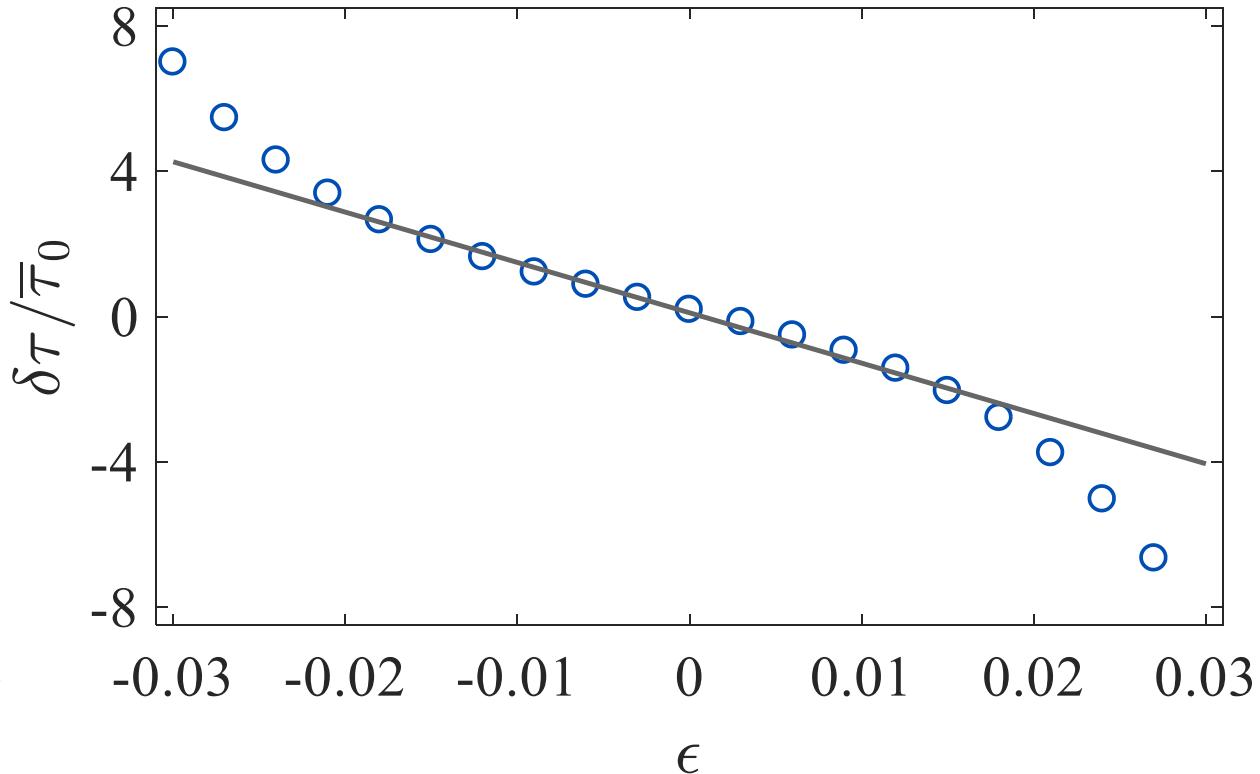
Sensitivity

$$\delta\tau = \tau_{\uparrow} - \tau_{\downarrow}$$

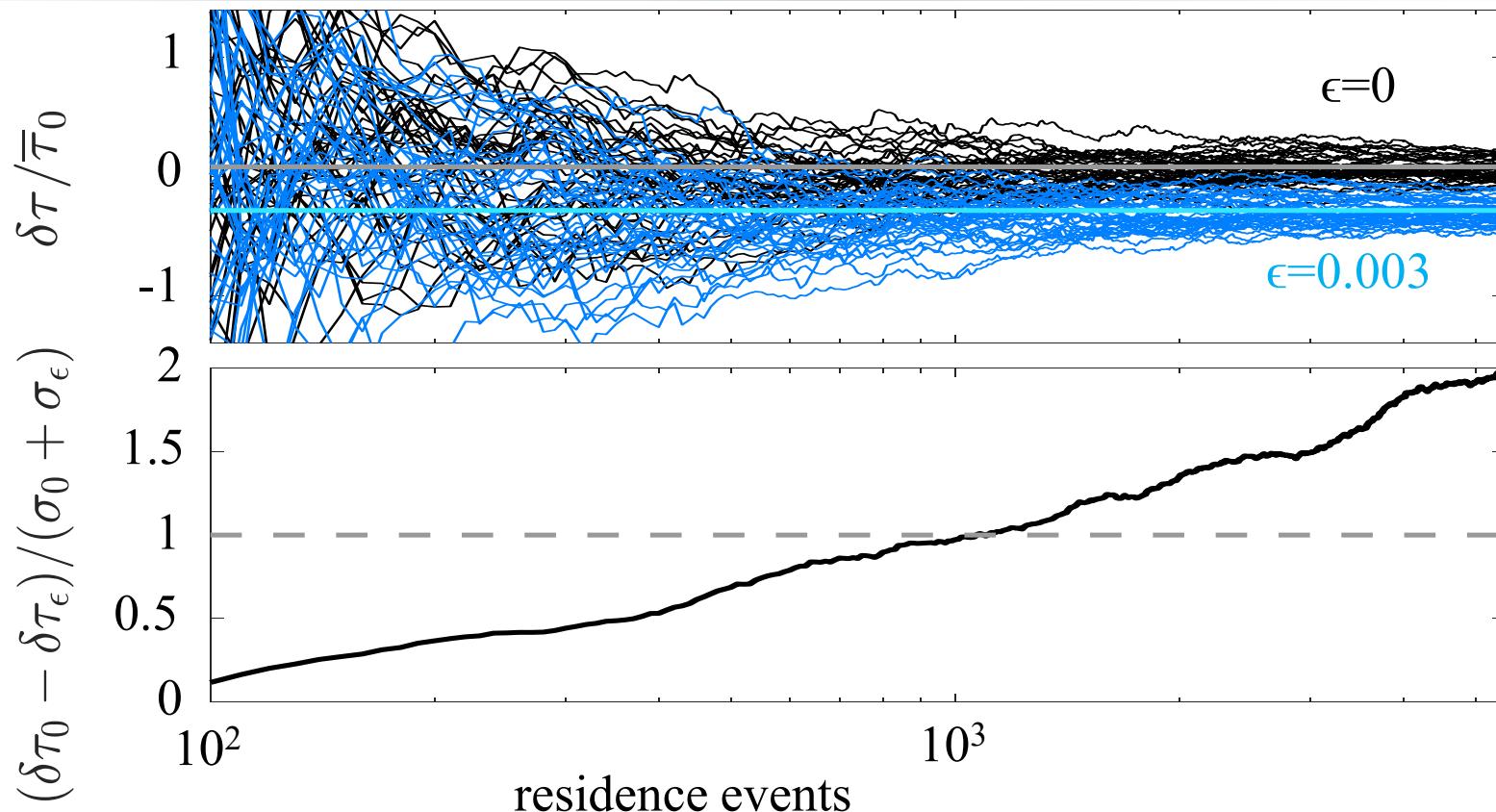
$$\bar{\tau}_0 = \frac{\tau_{\uparrow}(\epsilon = 0) + \tau_{\downarrow}(\epsilon = 0)}{2}$$

$$S = \frac{\partial \delta\tau}{\partial \epsilon} = 139 \text{ s}$$

Based on 4000 residence events
and 100 noise realizations

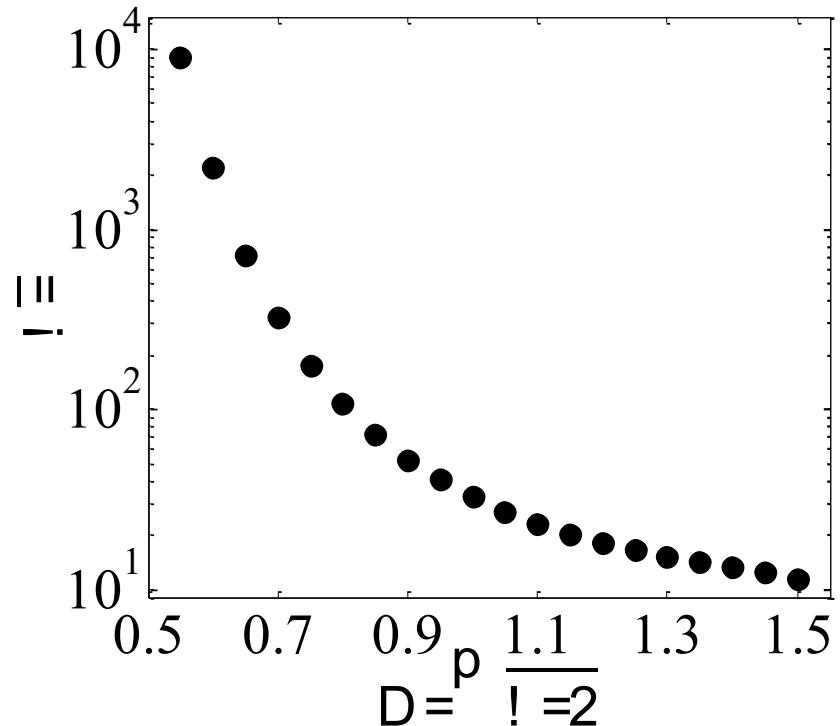


How much time we need to measure to detect a certain perturbation?

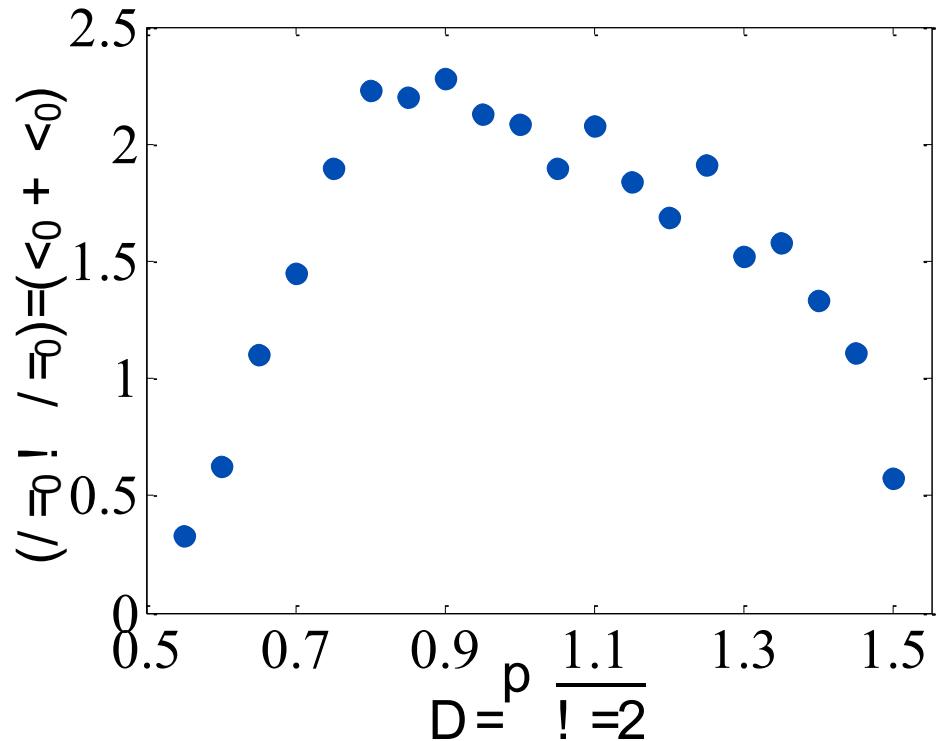


Detection speed & sensitivity

Detection speed increases with noise strength



Maximum sensitivity for finite noise strength



Thank you!



Veni, Vidi, Vici

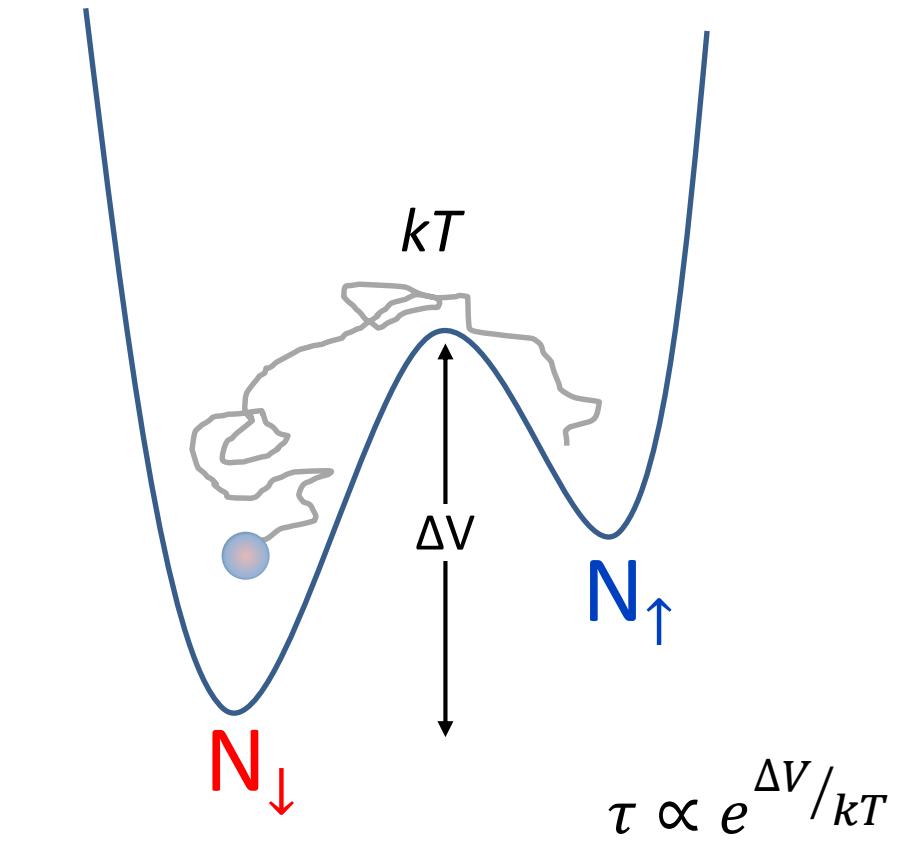
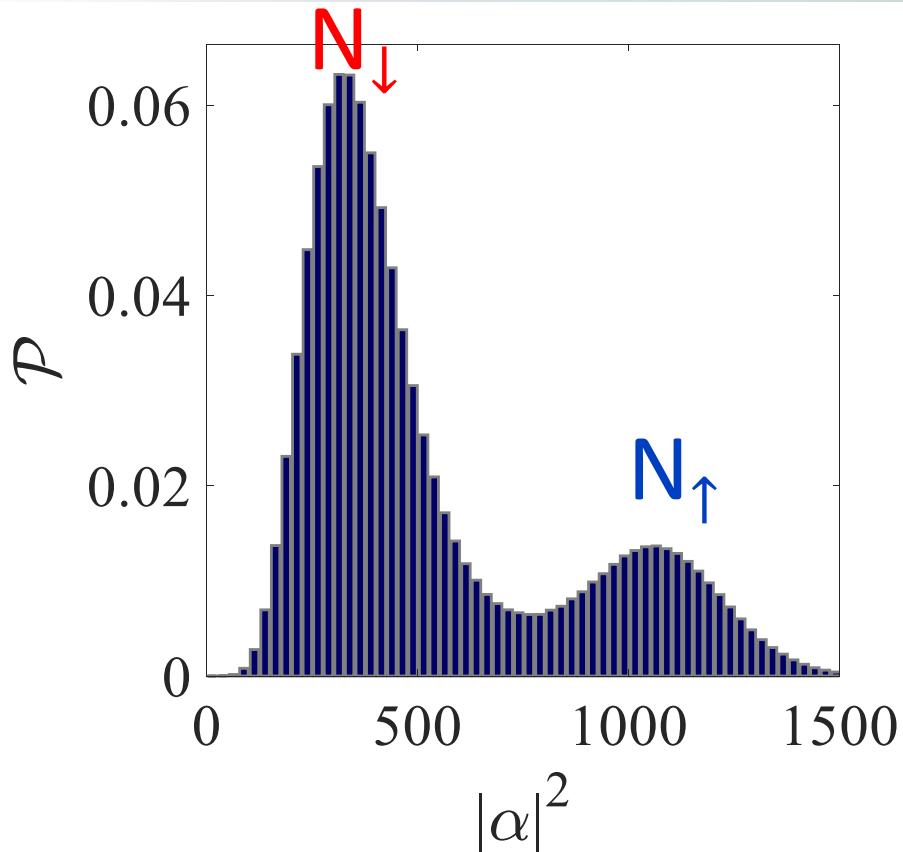
arXiv:1908.05521

www.amolf.nl

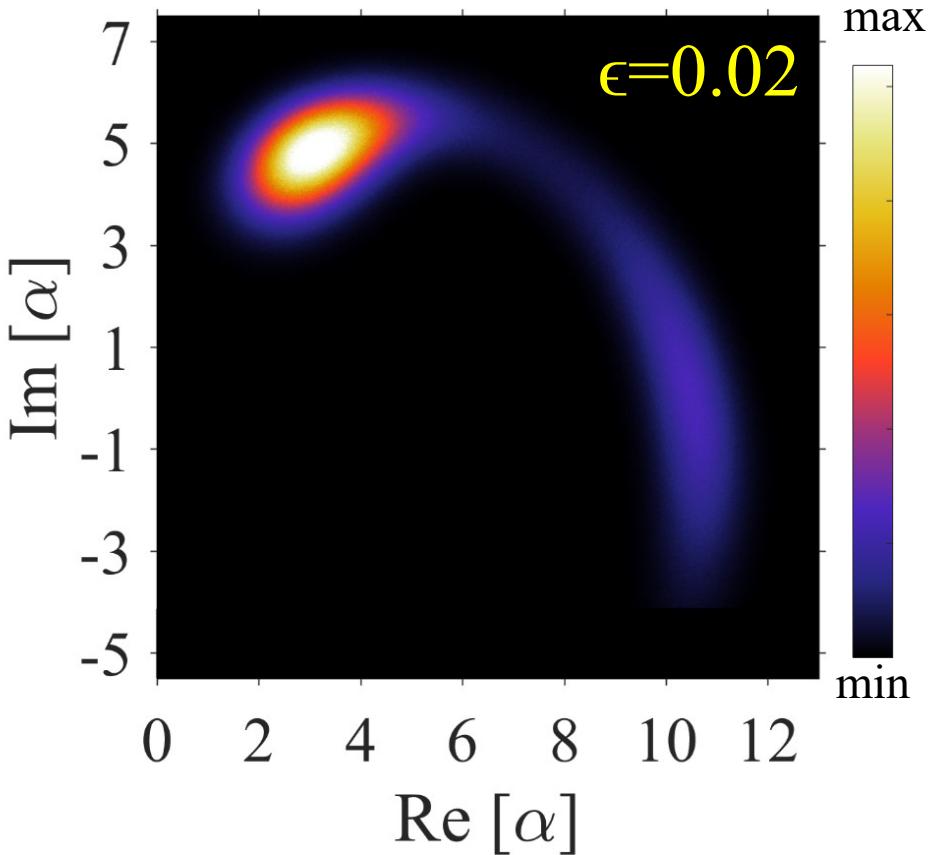
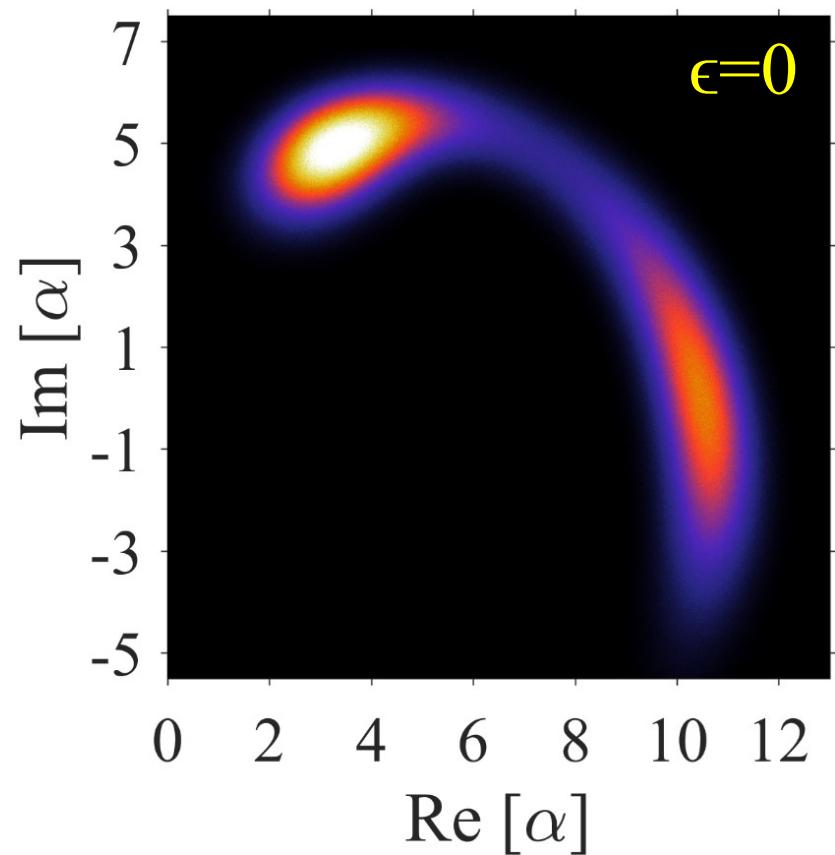
www.srkrodriguez.eu

Back-up slides

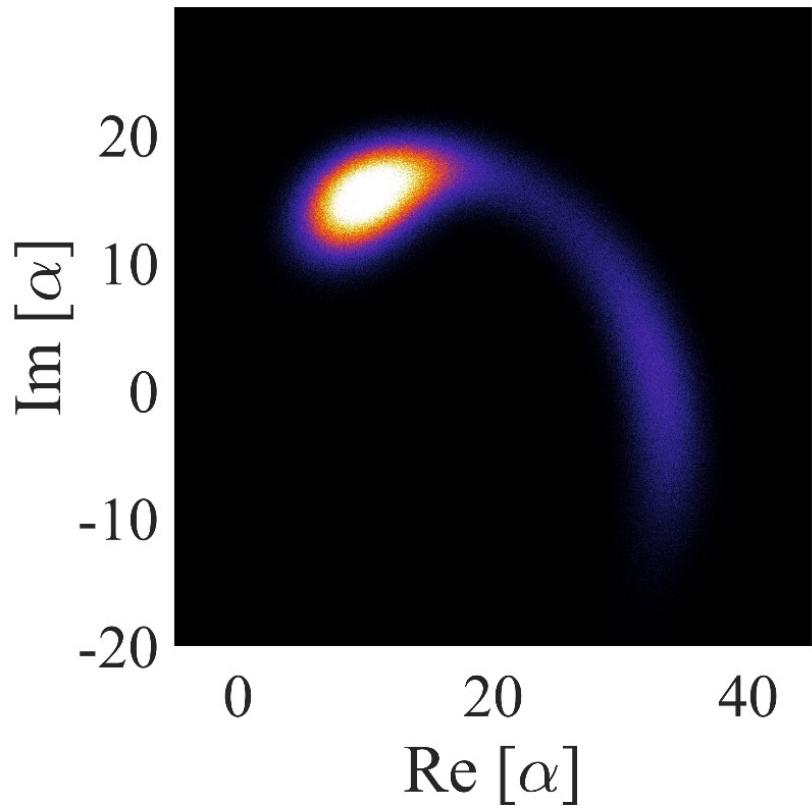
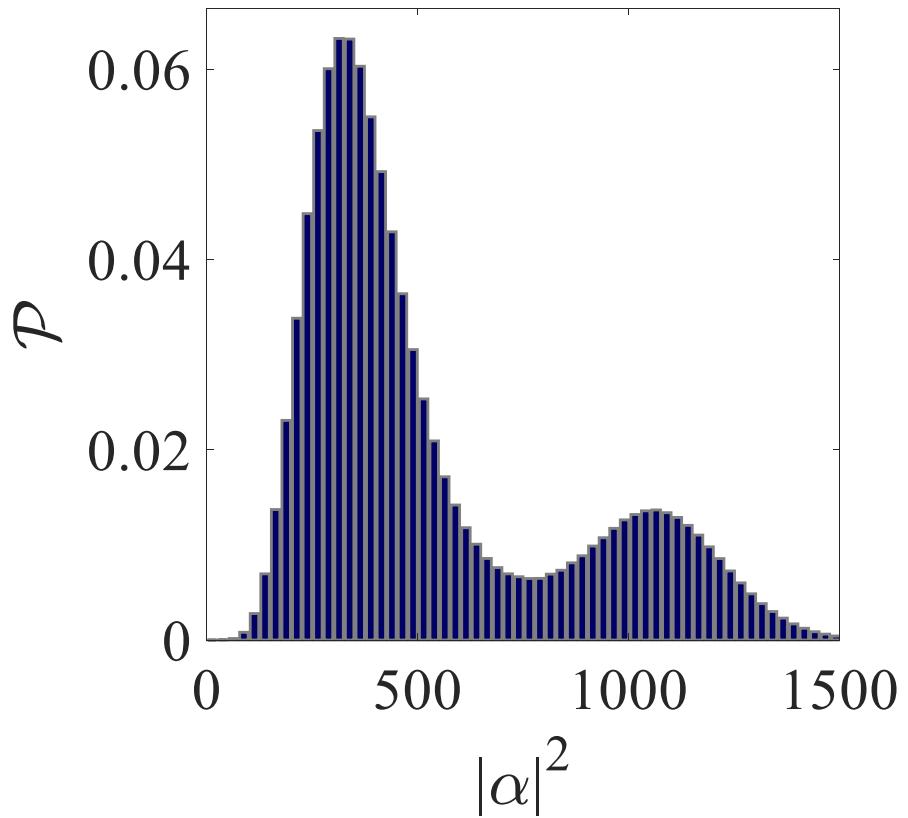
Analogy with a Brownian particle in a DWP



A perturbation tilts the effective DWP



Probability densities



Residence time statistics

